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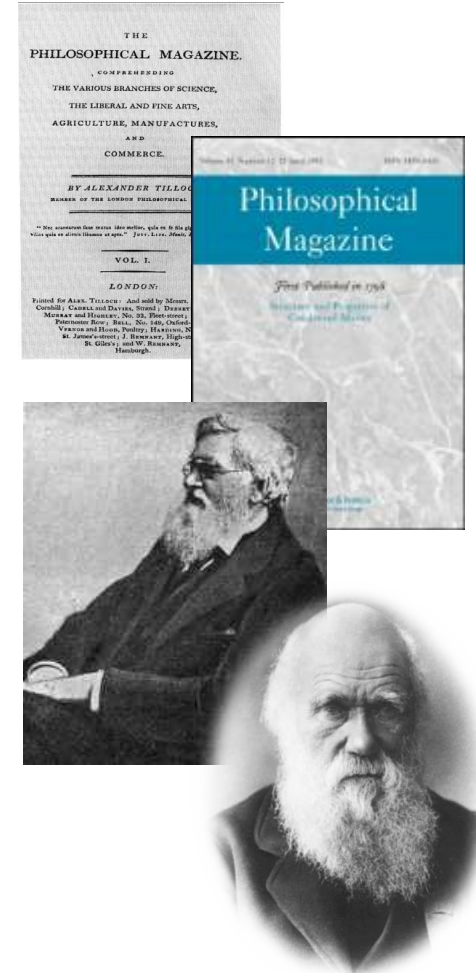


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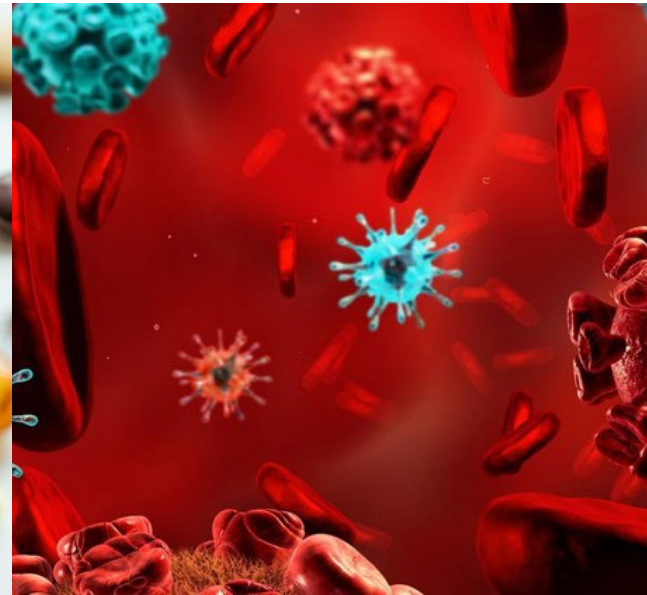
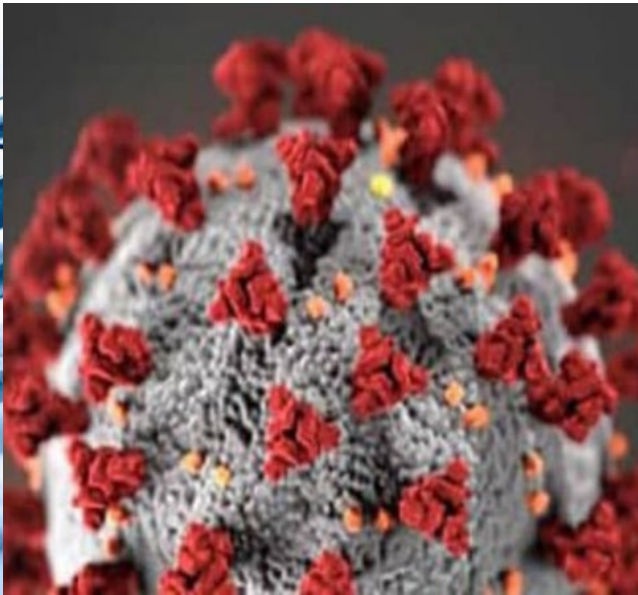


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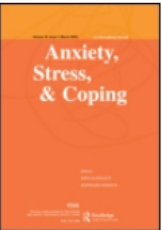
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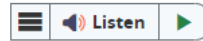
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Kenneth W. Clements & Maxwell Maesepp

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IV. Cyclone Larry
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Abstract

This article introduces an inverse differential demand system that has exactly the same form as the corresponding direct version. Its application is illustrated with the case of Australian fruit, whose prices were substantially affected by Severe Tropical Cyclone Larry in 2006.

Keywords: inverse demand fruit prices

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I. Introduction

An inverse demand system expresses prices as a function of quantities and can be used when markets are supplied constrained.¹ This article introduces a case in which the form of the differential inverse is exactly the same of the corresponding direct demand system and applies it to fruit, whose prices were substantially affected by Severe Tropical Cyclone Larry in 2006.

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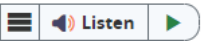
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Alina Averchenkova, Sam Fankhauser & Jared J. Finnegan

Pages 251-263 | Received 18 Jan 2020, Accepted 31 Aug 2020, Published online: 16 Sep 2020

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3. Policy certainty

4. Impact on the
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ABSTRACT

This paper assesses the importance of a strategic legal framework for action against climate change, using the UK *Climate Change Act* as an example. Passed in 2008, the *Climate Change Act* is one of the earliest and most prominent examples of framework legislation on climate change. It contains several innovative features that have since been replicated in other framework laws. We use stakeholder interviews to assess the strengths of the Act and whether it has succeeded in creating an integrated, informed and forward-looking policy process. Respondents felt that the Act had established a firm long-term framework with a clear direction of travel. However, they differed on whether the Act provided sufficient policy certainty and protection against political backsliding. Most respondents felt that the Act had changed the institutional context and the processes through which climate change is addressed. As a result, interviewees believe that

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Swinging mass for energy-efficient quadrupedal locomotion

Ito, Kazuki, Tsuboi, Shoki, Kawasetsu, Takumi & Hosoda, Koh

Advanced Robotics, 2023, Accepted 29 May 2023, Published online: 26 Jun 2023

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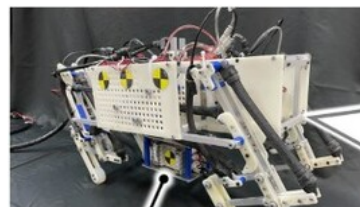
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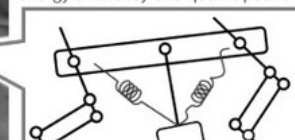
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Abstract

Quadrupedal animal, such as dogs, typically have soft but heavy abdomens, whose swinging motion significantly contribute to the energy efficiency of their entire locomotion. This study examines the effect of a swinging mass on quadrupedal locomotion by simulating the soft abdomen of its biological counterparts. A quadruped robot is designed with a swinging mass beneath its trunk. Its pitching motion was evaluated by a mechanical model. The experiment results demonstrate that the swinging mass effectively reduces the pitching motion, thereby improving the energy efficiency of the robot. Although the swinging mass does not always guarantee the energy efficiency of locomotion, the spring stiffness that supports the mass can be obtained for energy-efficient locomotion.



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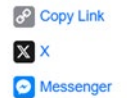
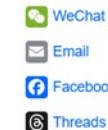


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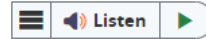
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Osaka University, Toyonaka, Osaka, Japan

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Hiroaki Tanaka & Koh Hosoda

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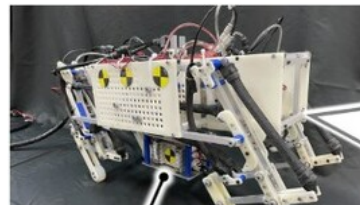
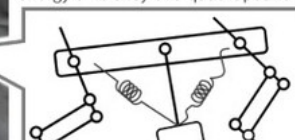
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
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KEYWORDS

Quadruped robot

energy-efficiency

swinging mass

pneumatic artificial muscle

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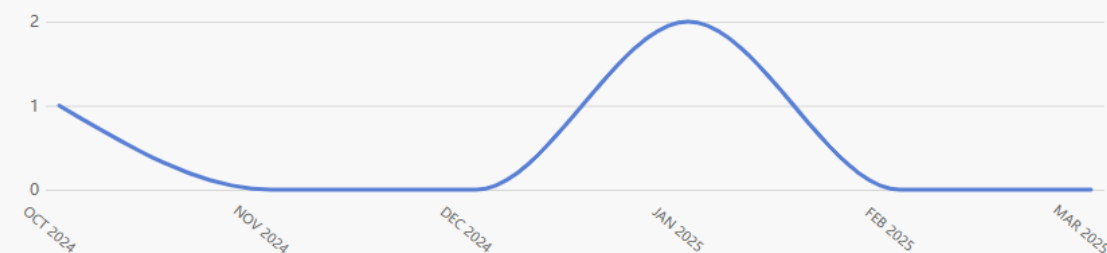
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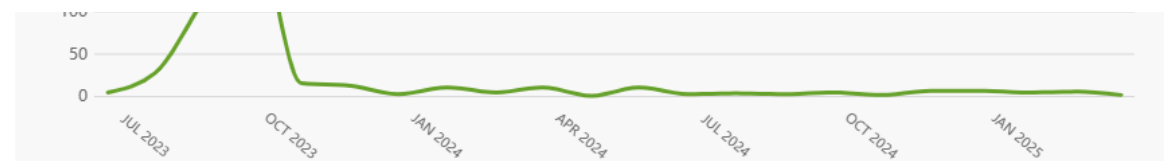
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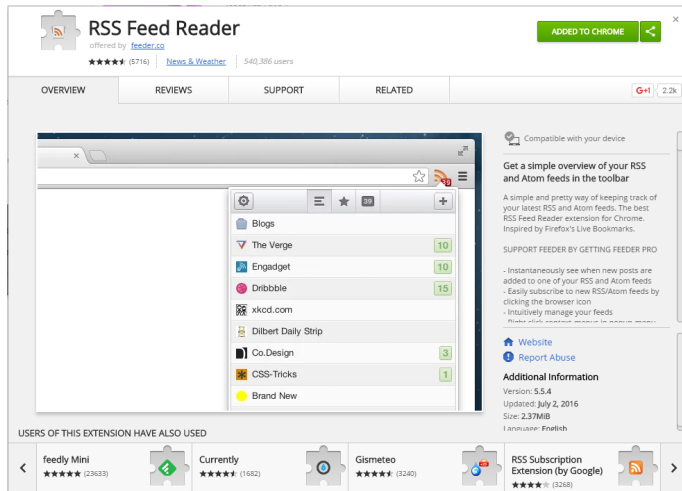
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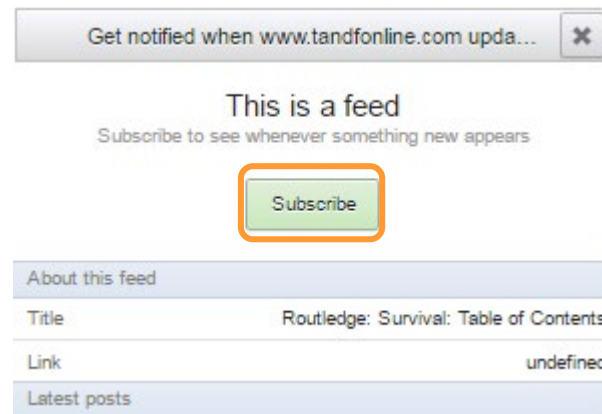
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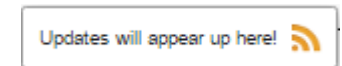
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
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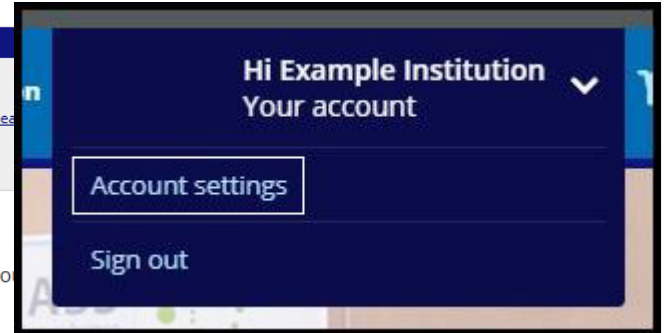
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